

Organic Computing Status and Outlook

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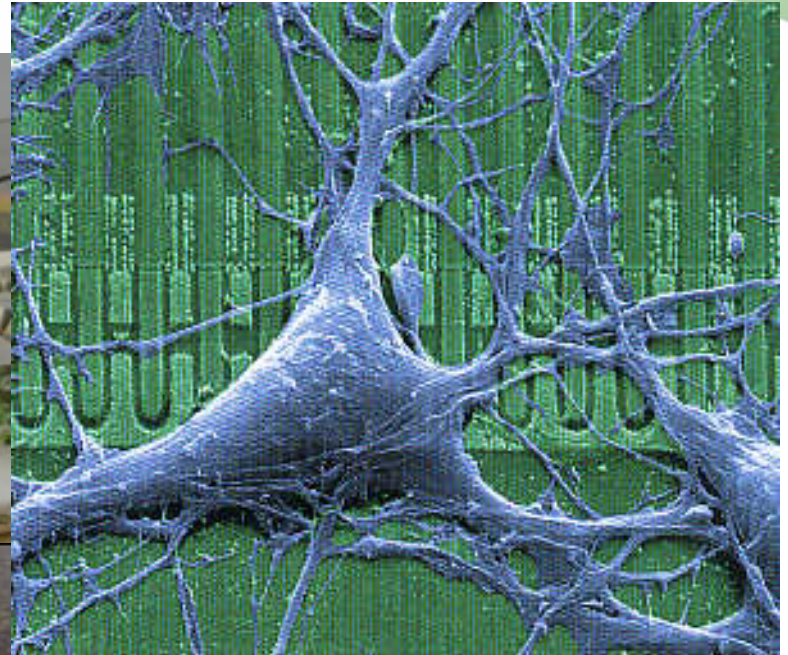
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Overview

- Vision
- Status
- Outlook
- Conclusion

What Organic Computing is *not about*



So, what is it about?



- Collections of **intelligent (embedded) systems** (scenarios like **smart house, car, office, factory, shop, healthcare, ...** **...ubiquitous, pervasive computing**).
 - Potentially **unlimited networks** (large number, mobility)
 - **Spontaneous local interaction**, leading to unexpected global behaviour (**emergent phenomena** as a result of **self-organisation**)
 - **Robust services** in dynamically changing environments (e.g. mobile communication).
 - **Flexible behaviour** as a reaction to varying external constraints (e.g. traffic light control)
 - **Design, management and acceptance problems** wrt increasingly **complex systems**
 → **Controllability? Trustworthiness?**
- ⇒ **We have to come up with good ideas for**
- **designing, managing, and controlling unlimited, dynamical networks of intelligent devices,**
 - **utilising the available technology for the utmost benefit to humans.**



- **Organic Computer Systems**

- will possess lifelike properties.
- will consist of autonomous and cooperating sub systems and will work, as much as possible, in a self-organised way.
- will adapt to human needs,
- will be robust, adaptive, and flexible,
- will be controlled by objectives (“goal-driven”),
- will provide customized service in a user-friendly way,
- will be trustworthy.

- **Self-organisation** allows for adaptive and context aware behaviour:

- self-configuring
- self-protecting
- self-optimizing
- self-explaining
- self-healing
- self-managing
- ...

Meta-data?

Model-predictive?

Controlled-self-organized?

Model-based?

Organic Computing

You-name-it...

Feedback control?

Policies?

Self-managing?

It is not the question,
whether adaptive and self-organising systems
will emerge,
but *how* they will be designed and controlled.

Autonomic?

Feedforward control?

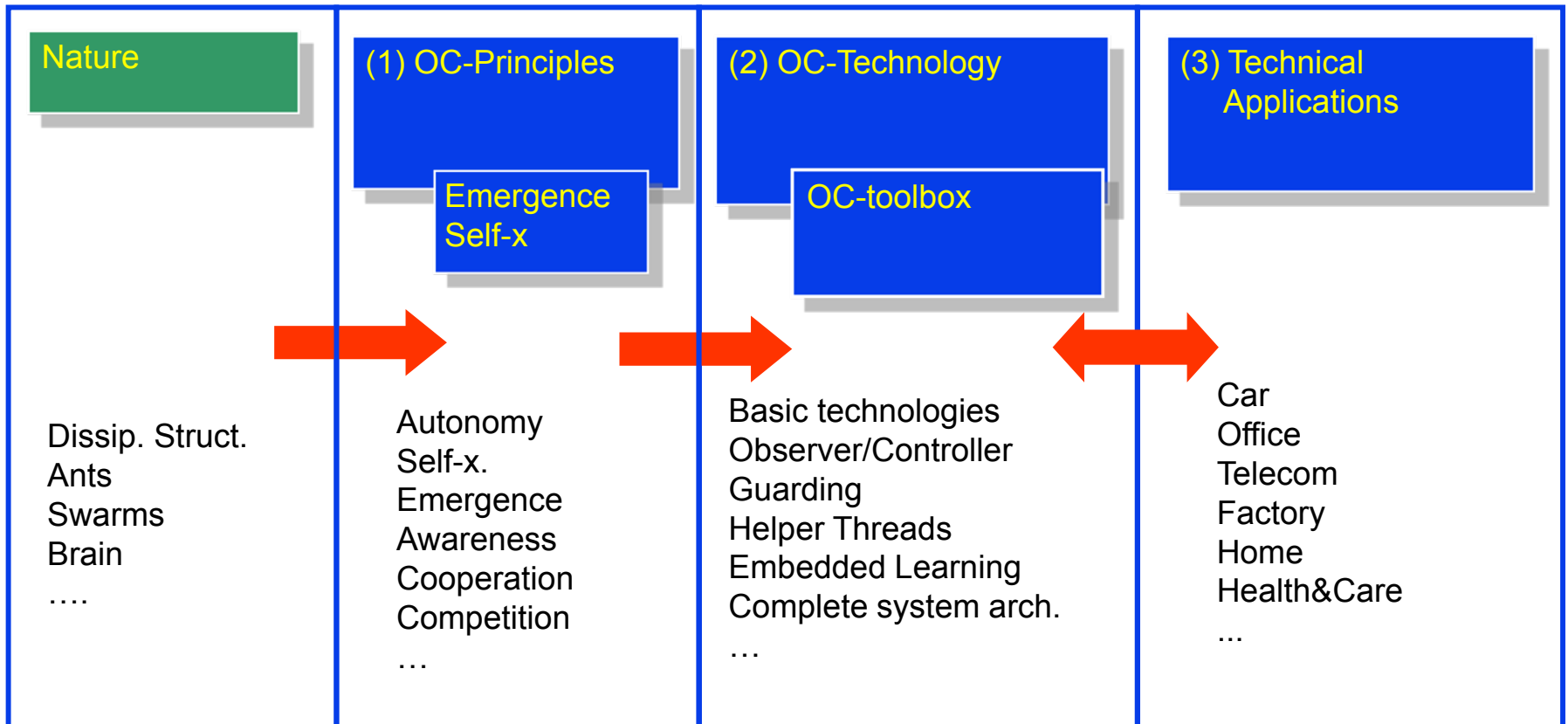
Self-adaptive?

Self-organized?

Emergent control?

German Framework for Research on OC :

DFG priority program 1183 „Organic Computing“ (2005 – 2011)
 currently 19 projects (Phase II), ~2 Mio€ per year
www.organic-computing.de/SPP



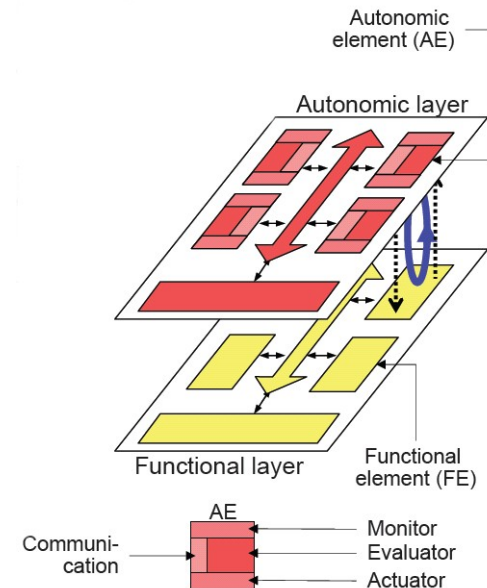
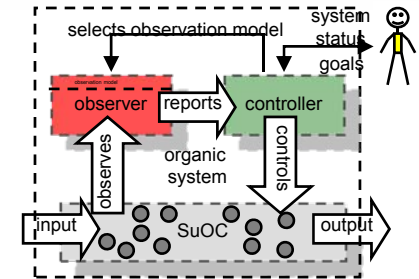
Phase II: 19 Projects

- **Learning to Look at Humans** (Würtz, Uni Bochum)
- **Model-Driven Development of Self-Organizing Control Applications** (Heiß, Mühl, TU Berlin, Weis Uni Duisburg)
- **Organic Fault-Tolerant Control Architecture for Robotic Applications** (Maehle, Brockmann, Uni Lübeck, Großpietsch FhG, St. Augustin)
- **Smart Teams: Local, Distributed Strategies for Self-Organizing Robotic Exploration Teams** (Meyer auf der Heide, Schindelhauer, Uni Paderborn)
- **Formal Modeling, Safety Analysis, and Verification of Organic Computing Applications – SAVE ORCA** (Reif, Uni Augsburg)
- **Embedded Performance Analysis for Organic Computing** (Ernst, TU Braunschweig)
- **OCCS - Observation and Control of Collaborative Systems** (Branke, Schmeck, KIT; Hähner, Müller-Schloer Uni Hannover)
- **OTC² - Organic Traffic Control Collaborative** (Hähner, Müller-Schloer, Uni Hannover, Branke, Schmeck Uni Karlsruhe)
- **AUTONOMOS: A distributed and self-regulating approach for organizing a large system of mobile objects** (Fekete, TU Braunschweig, Fischer, Uni Lübeck)
- **Organisation and Control of Self-Organising Systems in Technical Compounds** (Middendorf, Uni Leipzig)
- **Architecture and Design Methodology for Autonomic System on Chip** (Rosenstiel, Uni Tübingen, Herkersdorf, TU München)
- **Multi-Objective Intrinsic Evolution of Embedded Systems (MOVES)** (Platzner, Uni Paderborn)
- **OC μ - Organic Computing Middleware for Ubiquitous Environment** (Ungerer, Uni Augsburg)
- **The bio-chemical information processing metaphor as a programming paradigm for organic computing** (Dittrich, Uni Jena)
- **Energy Aware Self Organized Communication in Complex Networks** (Timmermann, Uni Rostock)
- **Generic emergent computing in chip architectures** (Fey, Uni Jena)
- **On-line Fusion of Functional Knowledge within Distributed Sensor Networks** (Sick, Uni Passau)
- **A Modular Approach for Evolving Societies of Learning Autonomous Systems** (Rammig, Kleinjohann, Uni Paderborn))
- **Digital On-Demand Computing Organism for Real-Time Systems** (Becker, Brinkschulte, Henkel, Karl, Uni Karlsruhe)

Status:

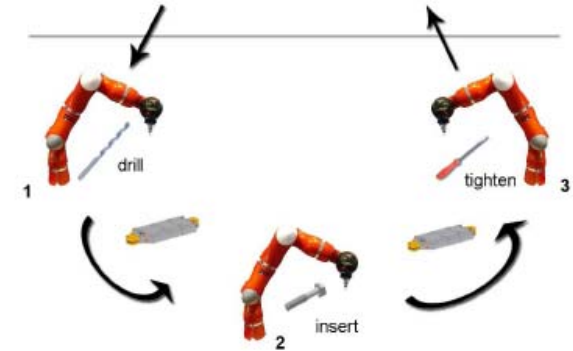
What did we achieve so far?

- Characterization and classification of emergence in SO-Systems (entropy-based)
(*Mnif, Müller-Schloer, Sick*)
- Characterization of basic properties of OC systems (autonomy, controlled self-organisation, adaptivity, robustness, flexibility,...)
(*Mühl, Müller-Schloer, Ortmeier, Schmeck, ...*)
- Design of a generic O/C-architecture
(*Branke, Mnif, Müller-Schloer, Richter, Schmeck, ...*)
- Design of generic OC-middleware components (OC μ , Artificial Hormone System – AHS)
(*Ungerer et al., Becker, Brinkschulte, Henkel, Karl*)
- Autonomic/Organic Systems on Chip
(*Herkersdorf, Rosenstiel et al.*)



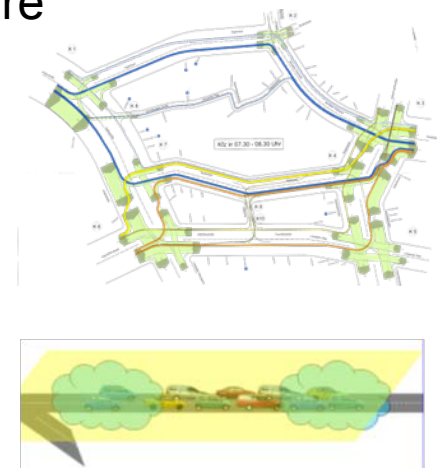
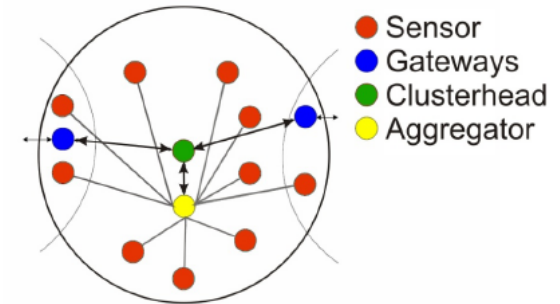
What did we achieve so far?

- Safety analysis and verification of OC-Applications
(*Reif et al.*)
- Formal definition and modeling of self-x systems; self-organizing algorithms and development tools for OC applications.
(*Heiß, Mühl, Weis*)
- Design of a self-configuring and self-healing robot
(*Brauckmann, Maehle et al.*)



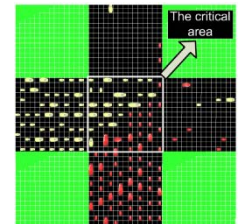
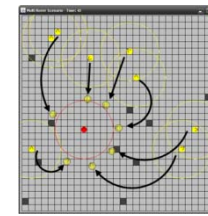
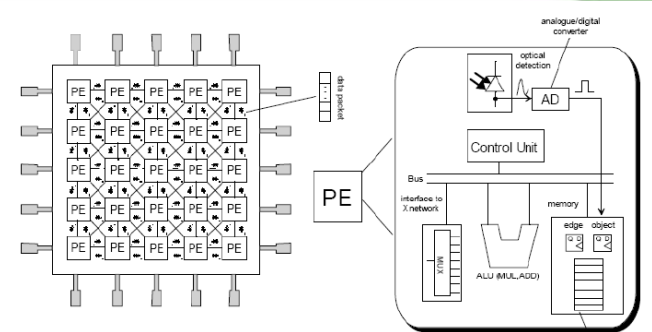
What did we achieve so far?

- Embedded performance analysis of OC-systems using a variant of the O/C-architecture (*Ernst*)
- Energy and resource aware self-organized communication and cooperation (smart teams, sensor networks) (*Timmermann et al., Meyer auf der Heide et al.*)
- Artificial immune systems, self-protection, self-healing (*Trumler et al., Timmermann*)
- Systematic investigation of self-organizing systems in nature (swarms of bees, bio-chemical information processing) (*Middendorf, Dittrich*)
- Application of OC principles in traffic (traffic light control, progressive signal chains, hovering data clouds, organic information complexes, Adaptable Distributed Strategies) (*Branke et al.; Fekete, Fischer*)



What did we achieve so far?

- Concept of Marching Pixels (MP), emergent algorithms, emergent computing (*Fey*)
- Principles, methods, and architectures for evolutionary self-adaptation to real-world problems (*Platzner*)
- Principles of collaboration, coordination and learning in multi-agent systems (*Branke, Hähner, Müller-Schloer, Schmeck,...*)
- Use of Classifier Systems for online learning (*Prothmann, Richter, Rochner, Zeppenfeld*)
- Analysis of emerging behaviour in evolving societies of learning autonomous systems (*Rammig et al.*)
- Autonomic learning of functional knowledge in sensor systems (*Sick*)
- Learning to find and track humans in video sequences and to recognize individuals (*Würtz*)



What did we achieve so far?

Joint work:

- Mini Workshops (13 so far)
- SPP working groups on
 - Architectures (*T. Ungerer*)
 - Applications (*W. Reif*)
 - Bio-inspired methods (*M. Middendorf*)
 - Design methods (*H.-U. Heiß*)
 - Self-organization and emergence (*C. Müller-Schloer*)

Work done?

Do we need new topics?

What did we achieve so far?

Impact , visibility of Organic Computing:

- Book on Organic Computing (ed. Rolf Würtz), Springer
- IEEE CIS Task Force on Organic Computing
- Dagstuhl Seminars on Organic Computing (next one end of 2010 or beginning of 2011)
- Workshops, special tracks, or thematical focus at conferences
 - GI Annual Conference
 - International Conference on Architecture of Computer Systems (ARCS)
 - ACM International Conference on Computing Frontiers
 - IFIP Conference on Biologically Inspired Cooperative Computing (BICC)
 - International Conference on Autonomic and Trusted Computing (ATC)
 - IEEE Congress on Evolutionary Computation (CEC)
 - IEEE International Conference on Self-Adaptive and Self-Organizing Systems (SASO)

Outlook:

Who will be in Phase III?

- Nobody knows so far, current situation:
 - 23 project proposals
 - 19 proposals for project continuation
 - 1 OC testbed proposal
 - 1 coordinator proposal
 - 3 new proposals
 - 1 additional proposal which might get associated
- Reviewer meeting **March 26, 2009**
(8 reviewers: 3 from Germany, 4 new reviewers)
- Hopefully, official decision by May or June, 2009

Outlook:

Where do we go beyond SPP 1183?

- **Topics of our working groups on Friday**
 - Lasting contributions of OC
 - Challenging topics that should be addressed based on the results of this SPP (Robustness, Trust,...)
 - Potential funding mechanisms/programs for future research on OC.
- Typical application areas for OC:
 - Traffic, automotive systems, machine management (→ program autonomik, BMWi)
 - Energy system, electro mobility
 - Logistics, production systems
 - Communication
 - Surveillance
 -

Conclusion

- SPP OC has produced a solid basis for further research and development projects
- OC technologies are applicable to a range of interesting application areas
- Research programs may be focused on application scenarios where OC is an enabling technology
 - Energy system
 - Machine management
 - Virtualisation (Cloud Computing,...)
 - ...
- We should cooperate to identify potential scenarios for further joint projects or research programs based on OC techniques.

Backup Slides:

Challenges for research on OC systems

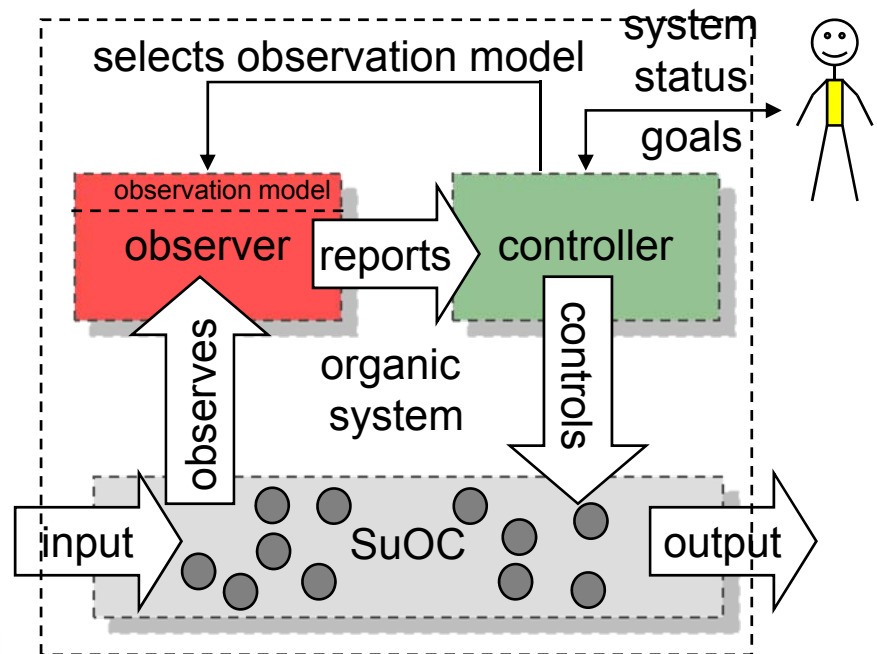
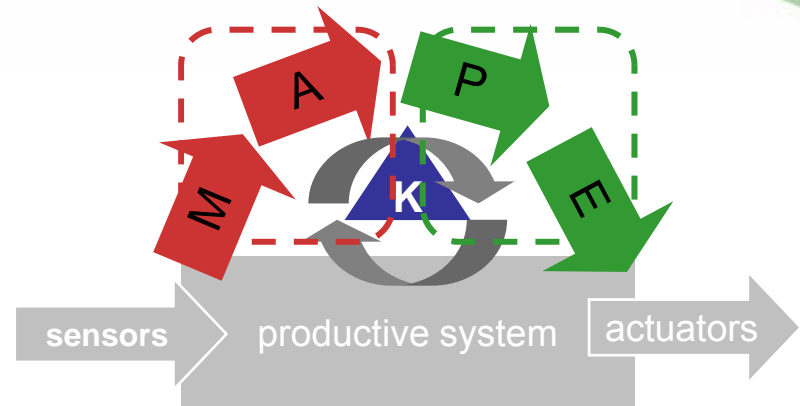
- Learning:
 - Potential of online- and offline learning
 - Collaborative learning
- Coordination and collaboration
 - Typical patterns of c & c in OC systems
 - Benefits, necessity of c & c
- Design
 - Finding the right balance between explicit design and degrees of freedom
 - Finding the right separation of concerns in hierarchical OC systems
- Cognition
 - Finding out “the needs of human users” (or, of the environment).
 - Detecting anomalies, distinguishing the “good” from the “bad”.

Challenges for research on OC systems (2)

- Control
 - Finding the right balance between “SO” and “control” phases.
 - Does “control by objectives” work?
- Trust
 - Can OC-systems be trustworthy?
 - Trust engineering?
- Assessment
 - Can there be “service level agreements” with guaranteed performance for OC-systems?
 - Benefits of OC versus “standard” designs?
 - Benchmark applications for OC
- ...

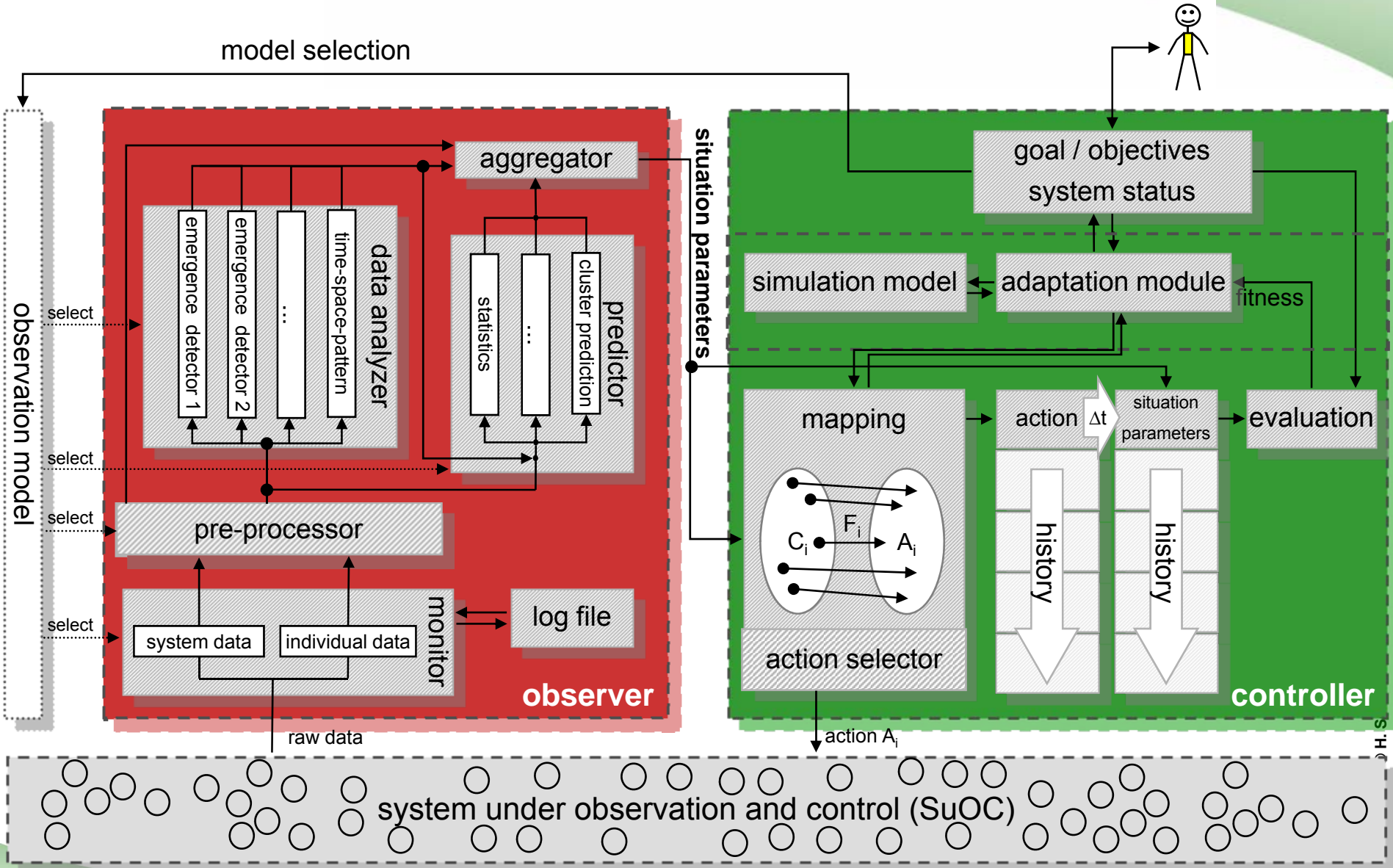
(Generic) Concepts for Control of SO-Systems

- IBM's **MAPE cycle** for autonomic computing
 - Monitor
 - Analyze
 - Plan
 - Execute
 - Knowledge
 (called "autonomic element")
- System under observation and control (SuOC)
 - A set of interacting elements/agents.
 - Does not depend on the existence of observer/controller.
- Distributed and/or central **observer/controller-architecture**
 - Driven by external goals
- Multilevel organization



Generic O/C-Architecture

J.Branke, M.Mnif, C. Müller-Schloer, U. Richter, H. Schmeck 2006

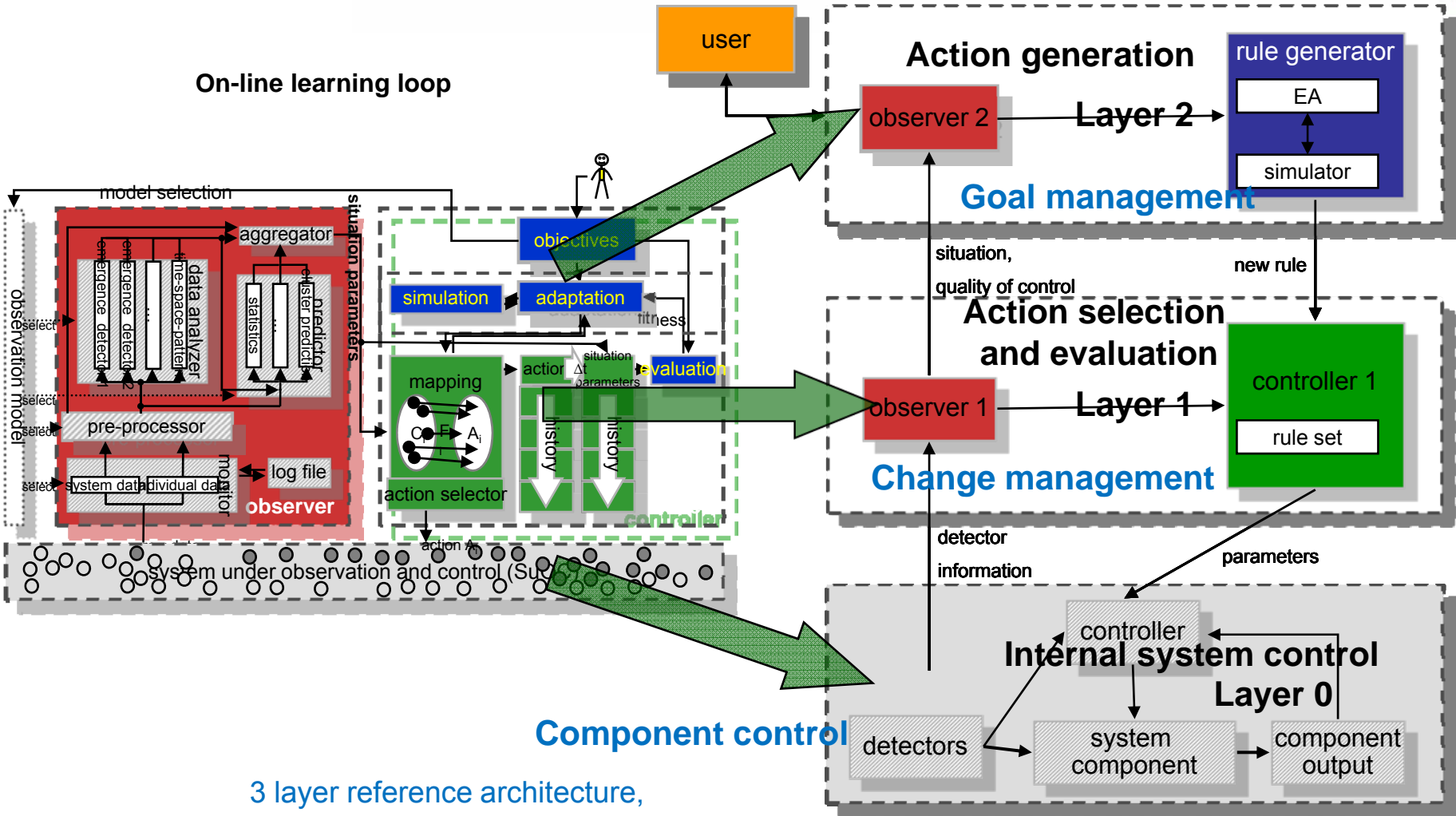


H. S.

Different view on O/C-architecture

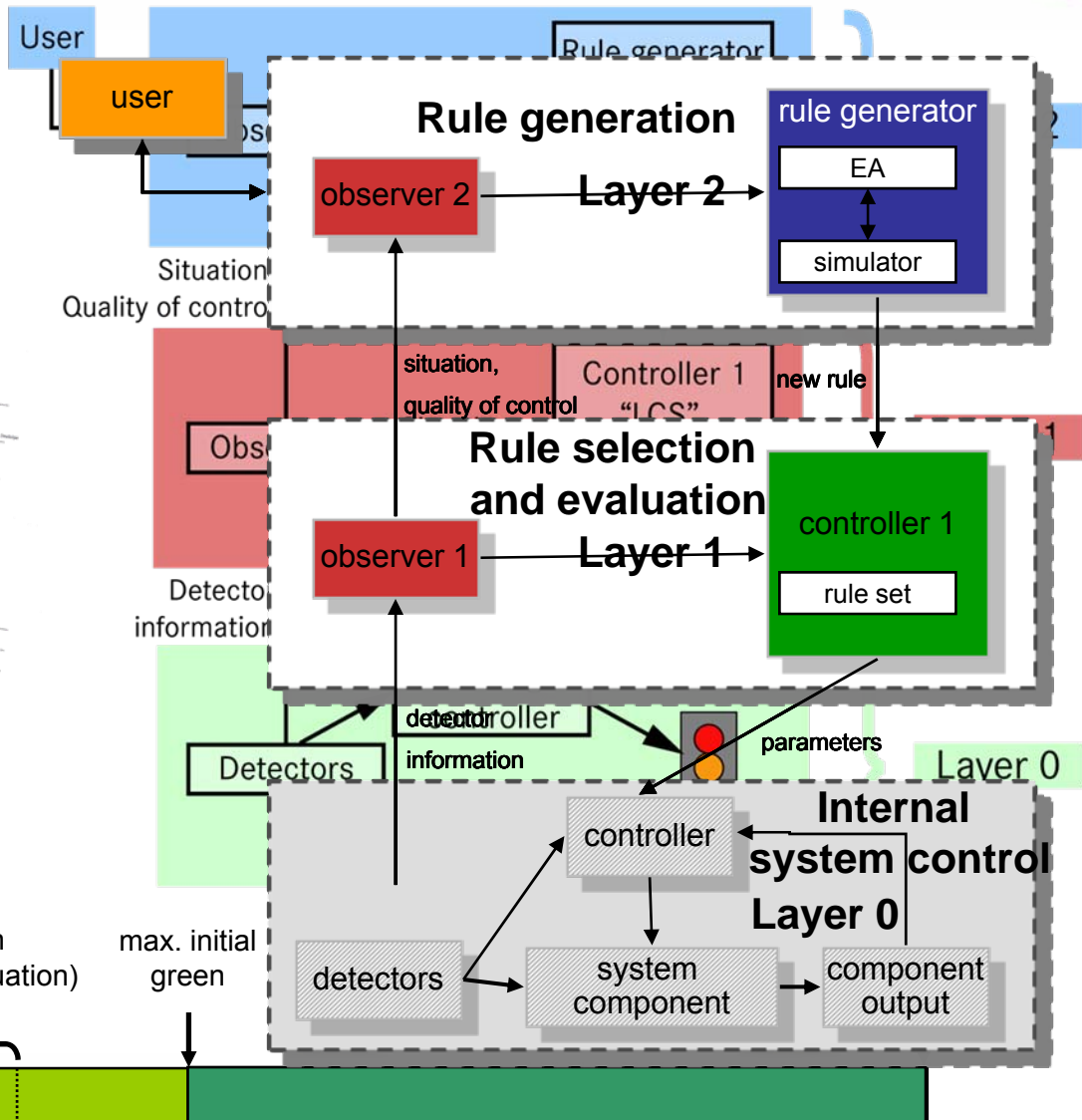
Off-line learning loop

On-line learning loop

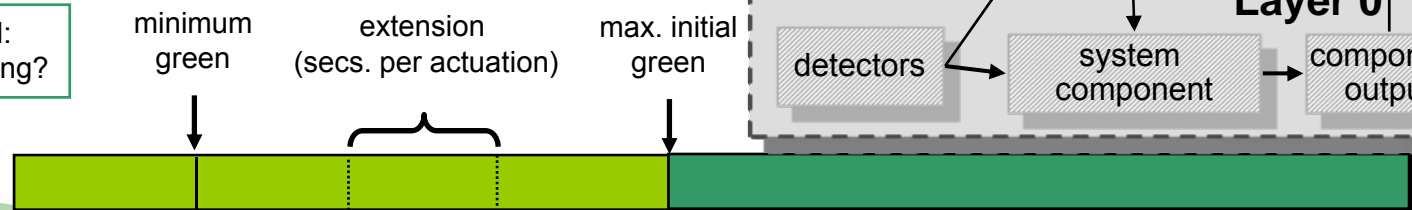


3 layer reference architecture, Jeff Magee, (DagSEfSAS 2008)

Example Application: Organic Traffic Control

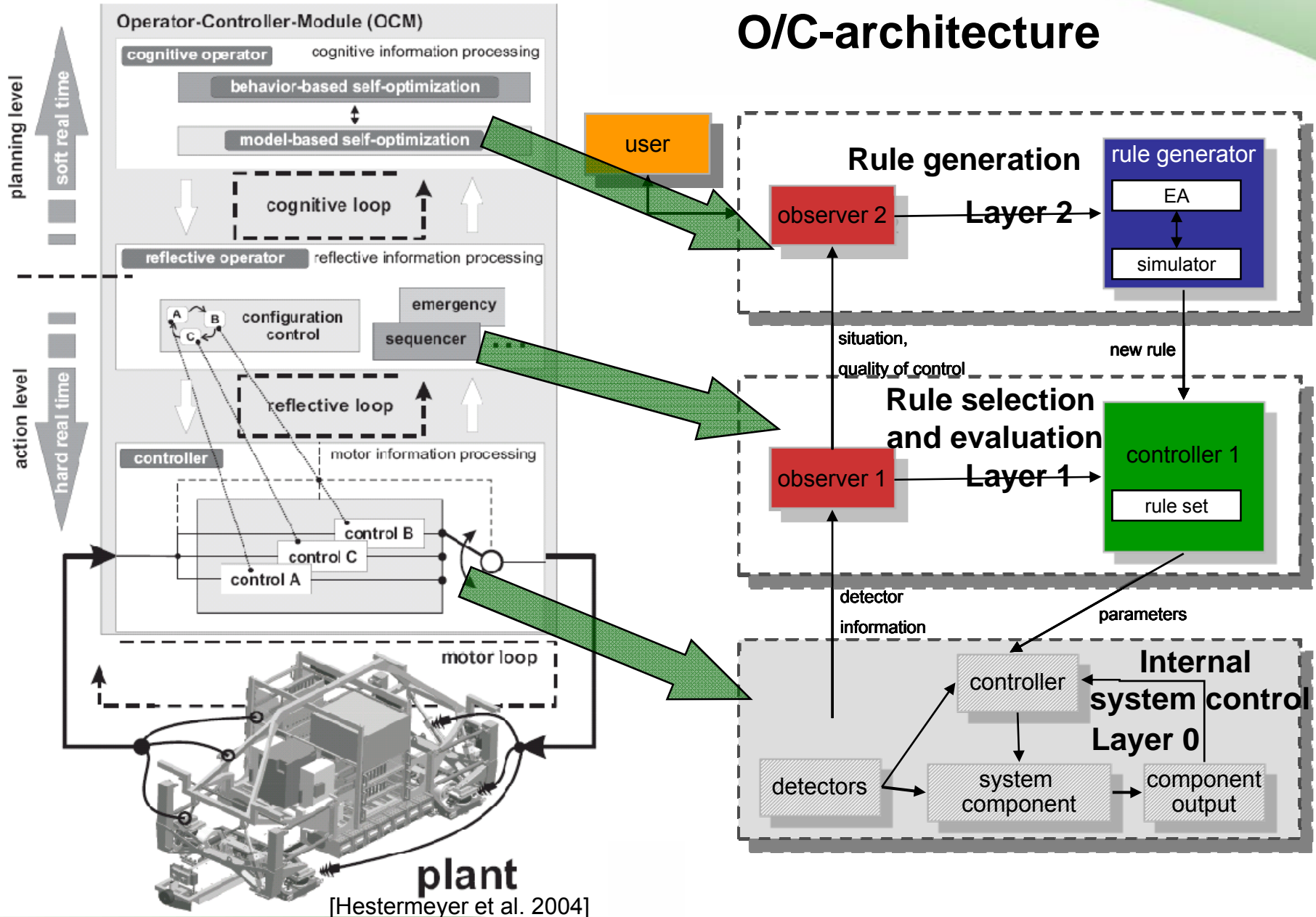


Recall:
car waiting?

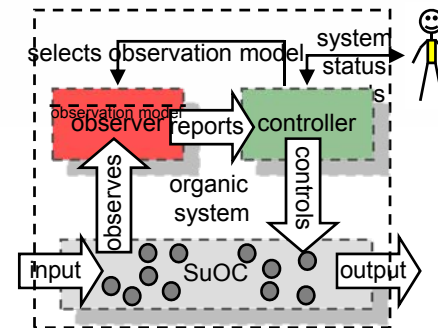


Operator-Controller Module

SFB 614 Paderborn



Remarks on O/C architecture

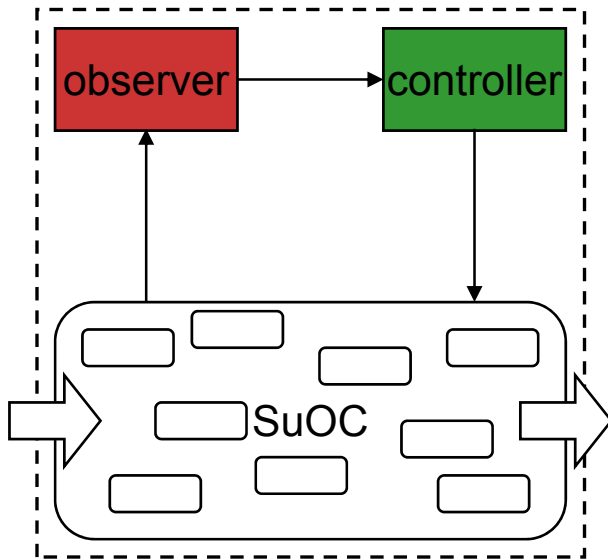


- Flexible template for observing, analysing, and influencing system behaviour.
- The potential of online and offline learning (Layers 1 and 2) should be explored in more application scenarios.
- The potential of modifying the model of observation and its consequences for controlling the system should be explored.
- There will be a roadmap of O/C architectures with growing capabilities, so far, only rather simple versions have been investigated.
- There is a need for more explicit support of communication and cooperation on the O/C-level(s).

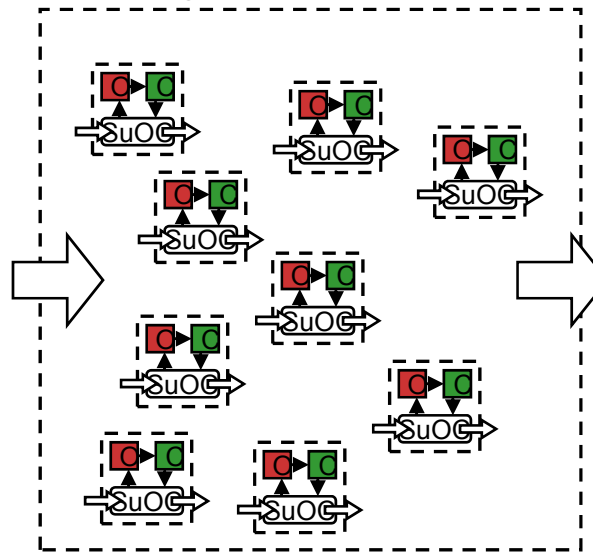
Realisation of OC systems

1. **Central:** One observer/controller for the whole system.
2. **Distributed:** An observer/controller on each system component.
3. **Multi-level:** An observer/controller on each system element as well as one for the whole system.

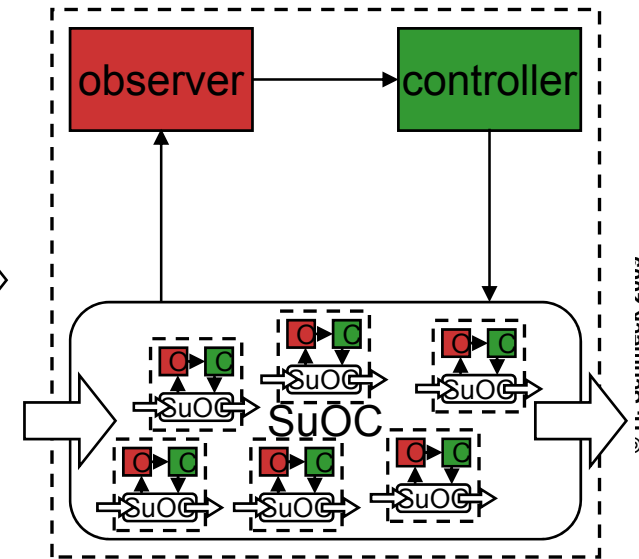
- adaptive
- top-down



- self-organising
- bottom-up
- emergent control



- controlled self-organising
- bottom-up / top-down



Types of control actions

1. **Control the environment** (e.g. speed limit in traffic)
2. **Control the communication** (messages, addresses, neighborhoods,...)
3. **Control the local behavior of components** (reconfigure HW, update software, modify skills, set new local objectives,...)

