

# Organic approaches to traffic control and route guidance

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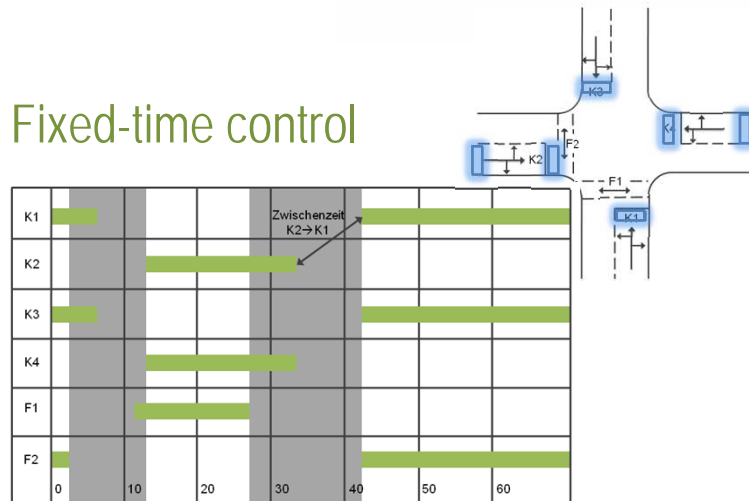
# Agenda



- Phase I – Traffic lights at intersections
- Phase II – Traffic lights in networks
- Phase III – Dynamic Route Guidance

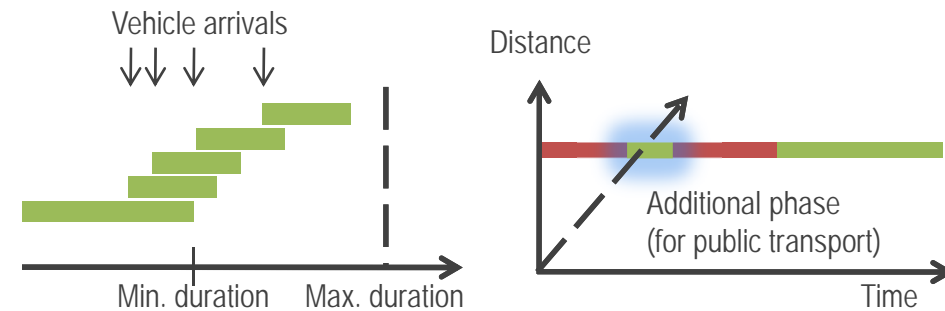
# Traffic nodes – State of the art

## Fixed-time control



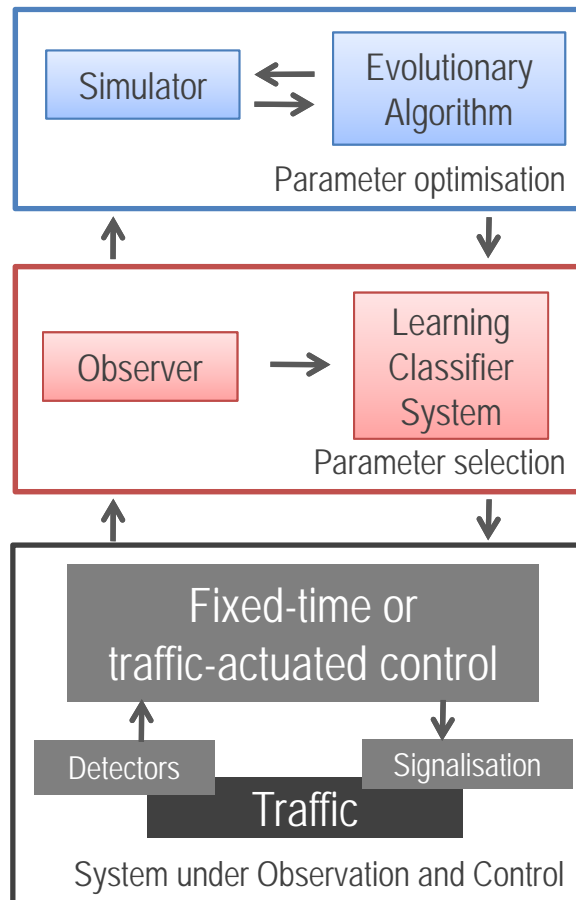
- No traffic-responsive control
- Day-time dependent switching
- Ageing of signal plans<sup>[1]</sup>:  
Deterioration of 3% per year  
w.r.t. delay

## Traffic-actuated control

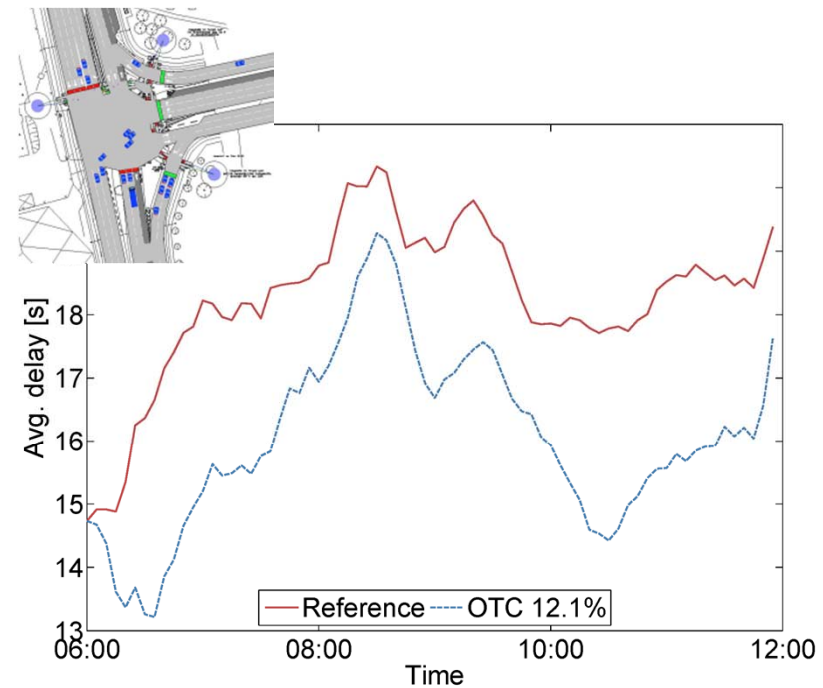


- Predefined logic
- Behaves like fixed-time control at high traffic demands
- No on-line evaluation / optimisation

# Organic traffic nodes<sup>[2]</sup>

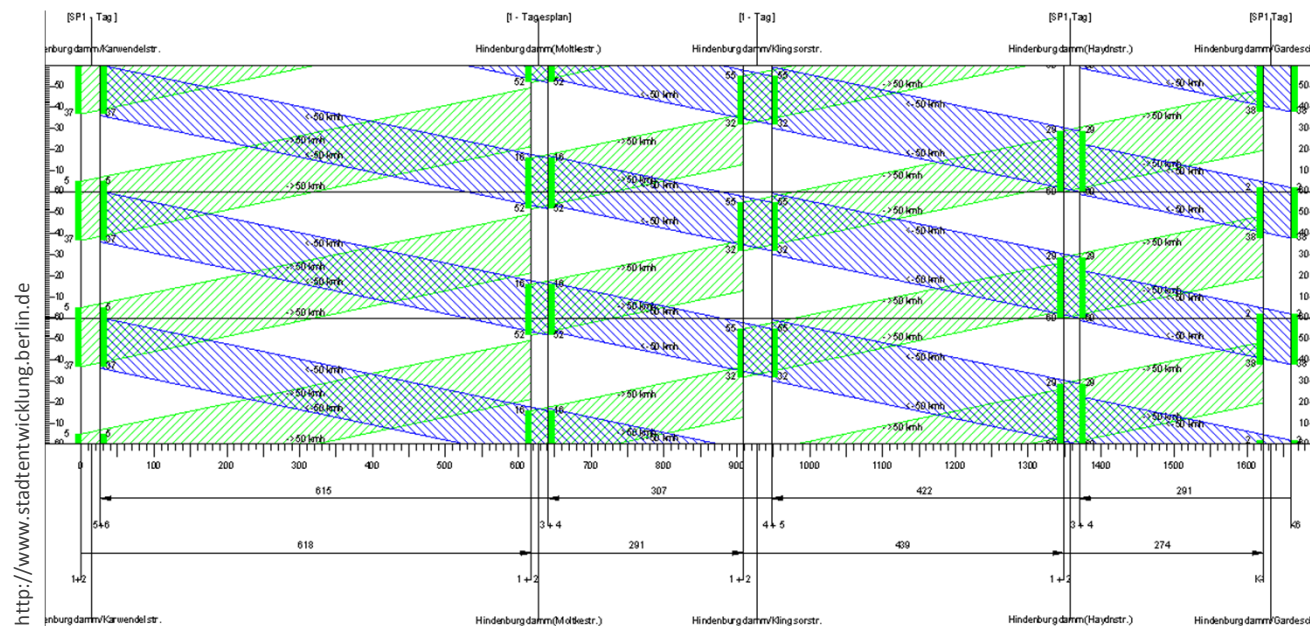


- On-line signal plan optimisation
- Reduced effort for maintenance
- Reduced delays



# Traffic networks – State of the art (1/2)

## Manual planning



Computer supported creation of time distance plots

- Not traffic-responsive
- Regular checks / recalculations necessary

# Traffic networks – State of the art (2/2)

## Adaptive network control systems

### SCOOT<sup>[3]</sup>

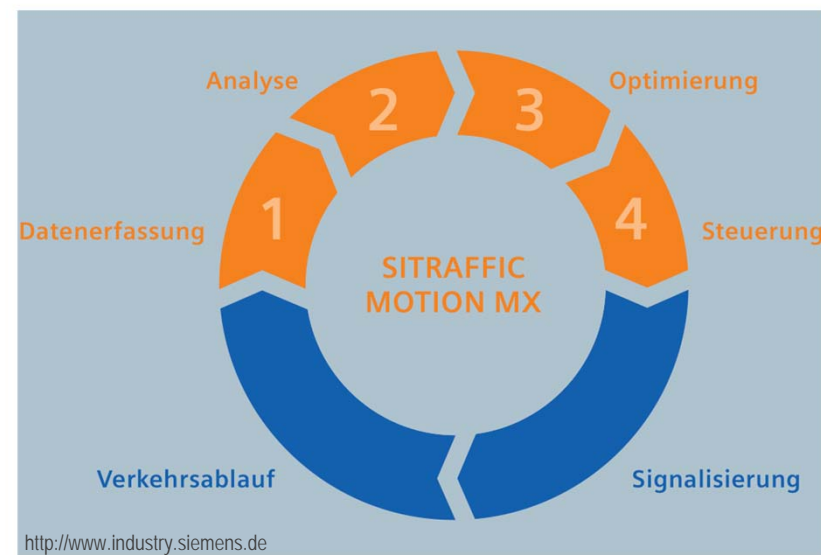
- Centralised optimisation of split, cycle, and offset
- High effort for communication<sup>[4,5]</sup>
- High susceptibility to failure<sup>[5]</sup>

### OPAC<sup>[6]</sup>

- Decentralised: Switching policies computed via dynamic programming
- No coordination among neighbouring intersections

## MOTION<sup>[5]</sup>

- Hierarchical system:
  - Network-wide optimisation (frame signal plan)
  - Local traffic-actuated control



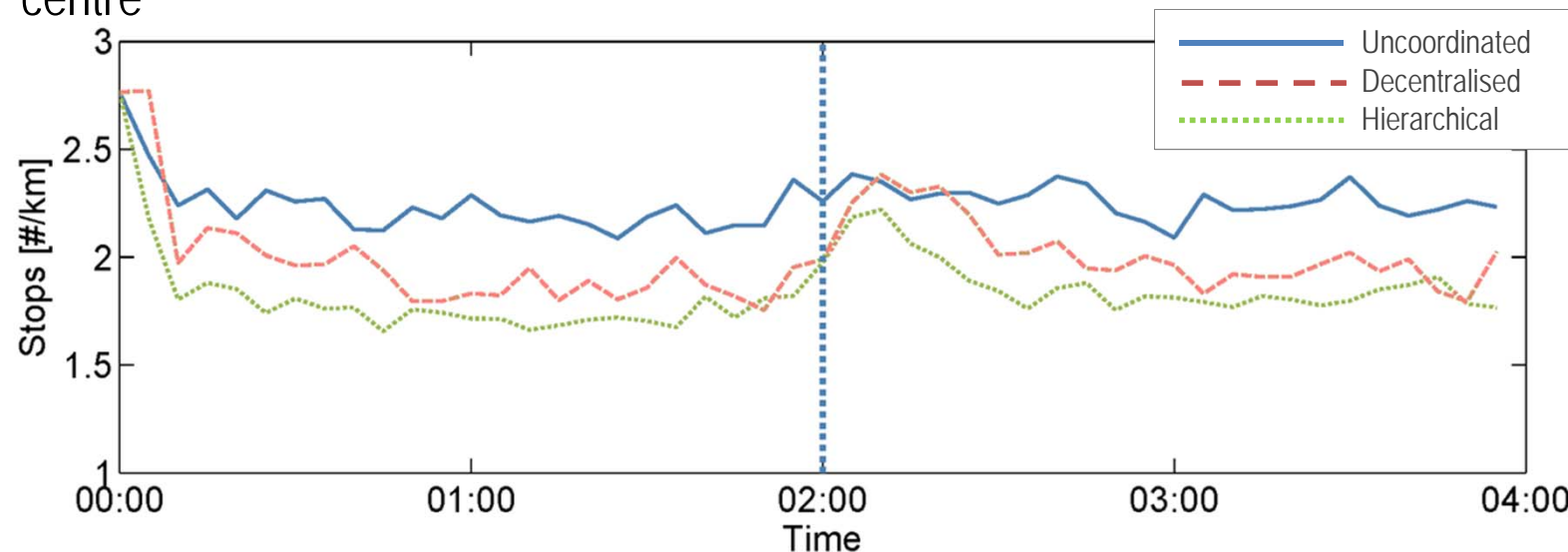
# Coordination in organic traffic networks

## Decentralised coordination<sup>[2]</sup>

- Local organic intersections
- Decentralised coordination
- Traffic-responsive coordination
- Reduced number of stops
- Avoids drawbacks of a traffic control centre

## Hierarchical coordination<sup>[7]</sup>

- Local organic intersections (i.e., **local on-line optimisation**)
- Additional Regional Manager supports the coordination
- Improved handling of special cases



# Dynamic Route Guidance (DRG)

## State of the art (in cities)

### Road users

- Individual navigation systems
- Travel-time database
- User-optimal routes (no network optimum)

### Authorities

- Variable Message Signs at selected locations
- Integration of DRG and centralised traffic control systems<sup>[8,9]</sup>
- Developments are not well documented!

## OTC3

### Decentralised DRG

- Neighbouring intersections communicate
- Individual recommendations based on
  - Current demands
  - Local information
- Similarities to Internet routing

### Hierarchical DRG

- Network-wide traffic prediction
- Incident detection
- Incorporate external goals
- System vs. user optimum



# Summary

## Phase I – Traffic lights at intersections

- On-line evaluation and optimisation of signal plans

## Phase II – Traffic lights in networks

- Traffic-responsive decentralised coordination

## Phase III – Dynamic Route Guidance

- Decentralised routing / individual recommendations based on current demands
- Hierarchical routing w.r.t. system optimum



# References

- [1] M. C. Bell and R. D. Bretherton. Ageing of fixed-time traffic signal plans. In Proc. 2<sup>nd</sup> IEE Conf. on Road Traffic Control, pages 77-80, 1986.
- [2] H. Prothmann, J. Branke, H. Schmeck, S. Tomforde, F. Rochner, J. Hähner, and C. Müller-Schloer. Organic traffic light control for urban road networks. *International Journal of Autonomous and Adaptive Communications Systems*, 2(3):203-225, 2009.
- [3] D. I. Robertson and R. D. Bretherton. Optimizing networks of traffic signals in real time – the SCOOT method. *IEEE Transactions on Vehicular Technology*, 40(1):11–15, 1991.
- [4] J. Mück. BALANCE: Adaptive Lichtsignalsteuerungen für Straßennetze und einzelne Knotenpunkte. In M. Steierwald und S. Martens, Hrsg., *Steuerung kommunaler Verkehrsnetze*, pages 53-66. Akademie für Technikfolgenabschätzung in Baden-Württemberg, 2003.
- [5] B. Friedrich. Steuerung von Lichtsignalanlagen: BALANCE – ein neuer Ansatz. *Straßenverkehrstechnik*, 44(7):321–328, 2000
- [6] N. H. Gartner. OPAC Strategy for demand-responsive decentralized traffic signal control. In J.-P. Perrin, editor, *Control, Computers, Communications in Transportation*, pages 241–244, 1989.
- [7] S. Tomforde, H. Prothmann, J. Branke, J. Hähner, C. Müller-Schloer, H. Schmeck. Possibilities and Limitations of Decentralised Traffic Control Systems. *Submitted to WCCI 2010*.
- [8] N. B. Hounsell, M. McDonald, and R. A. Lambert. The integration of SCOOT and dynamic route guidance. In *Proceedings of the IEEE Road Traffic Monitoring Conference*, pages 168-172, 1992.
- [9] G. Kruse. COSMOS – Results of the MOTION demonstrator for congestion and incident management strategies in Piraeus. In *Proceedings of Trakdage 1999*, 1999.

## Kritik an zentralen Systemen

“Häufig lassen sich einzelne Signalanlagen aufgrund ihrer Lage schon technisch nicht an eine Zentrale anbinden. In anderen Fällen kann der **Aufwand** [...] **unangemessen** sein, weil Verkehrsstörungen lediglich an einzelnen Knotenpunkten auftreten.”

J. Mück. BALANCE: Adaptive Lichtsignalsteuerungen für Straßennetze und einzelne Knotenpunkte. In M. Steierwald und S. Martens, Hrsg., *Steuerung kommunaler Verkehrsnetze*, Seiten 53-66. Akademie für Technikfolgenabschätzung in Baden-Württemberg, 2003.

“Die Erfahrung der jüngeren Forschung zeigt, daß **verteilte Intelligenz** der Komplexität des Verkehrs [...] häufig besser gerecht werden kann. Die Störanfälligkeit eines zentralen Systems sowie der enorme Aufwand, die relevanten Daten [...] zu übertragen, sind weitere Gründe dafür, neue Wege zu **effizienteren Systemarchitekturen** zu suchen.”

B. Friedrich. Steuerung von Lichtsignalanlagen: BALANCE – ein neuer Ansatz. *Straßenverkehrstechnik*, 44(7):321–328, 2000.

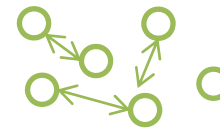
MOTION



RM



DPSS



SCOOT

