

# Autonomos

## Results of 1st Phase

## Research Objectives for 2nd Phase



Stefan Fischer  
Axel Wegener  
Horst Hellbrück

Institute of Telematics  
University of Lübeck



Sándor P. Fekete  
Christiane Schmidt

Algorithms Group  
Braunschweig University of Technology

# Overview

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The logo for AutoNOMOS is displayed in a blue, cloud-like shape at the top right of the slide. The text 'AutoNOMOS' is written in a white, sans-serif font. Below the logo, a network diagram is overlaid on a background image of a highway with traffic. The diagram consists of several nodes (small circles) connected by lines, representing a network structure.

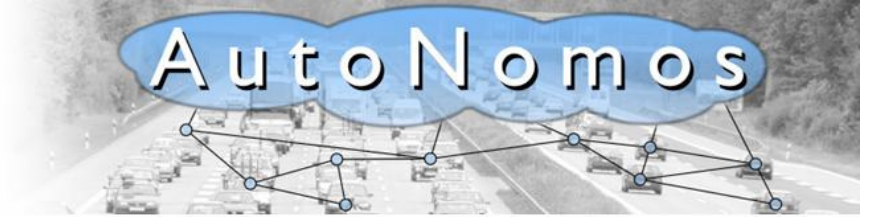
- Results of 1st Phase
  - Recognition of Traffic Jams
  - Transport Layer for Hovering Data Clouds
  - Mindstorms Demonstrator
- Research Objectives for 2nd Phase
  - Structures in Road Networks
  - Algorithms for Efficient Distributed Computing

# Motivation



- Basic Scenario:  
Traffic Jam
- Recognition of
  - Front and Back
  - Type
  - Temporal and Spatial Changes
- Transmit Proper Data to other Road Users
- For that Purpose:  
Hovering Data Clouds (HDCs)

# Motivation

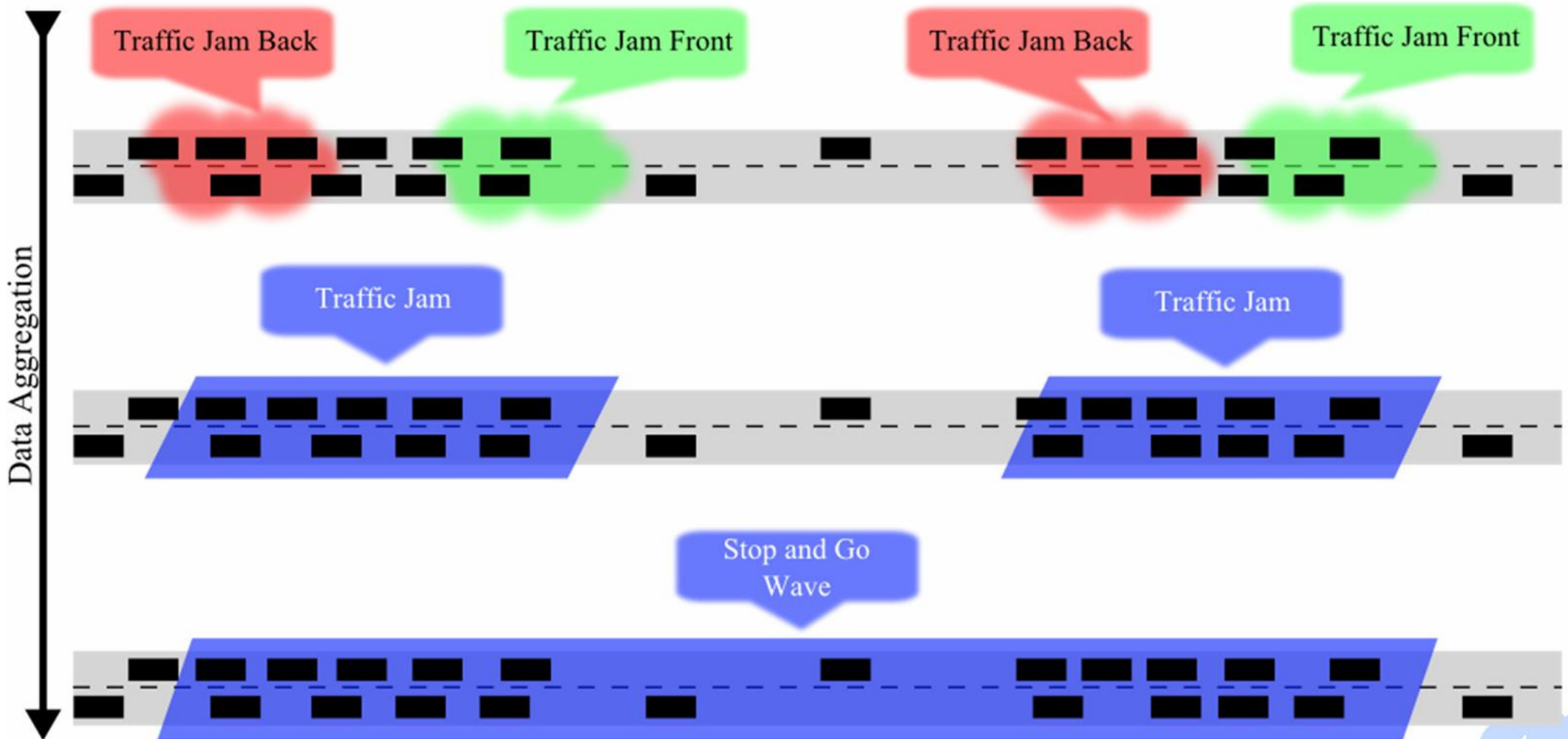


- Hovering Data Clouds
  - Form as a Result of a Certain Event
  - Hosted by individual Vehicles
  - But “Live” and “Evolve” independent of Them
  - Migrate from Vehicle to Vehicle

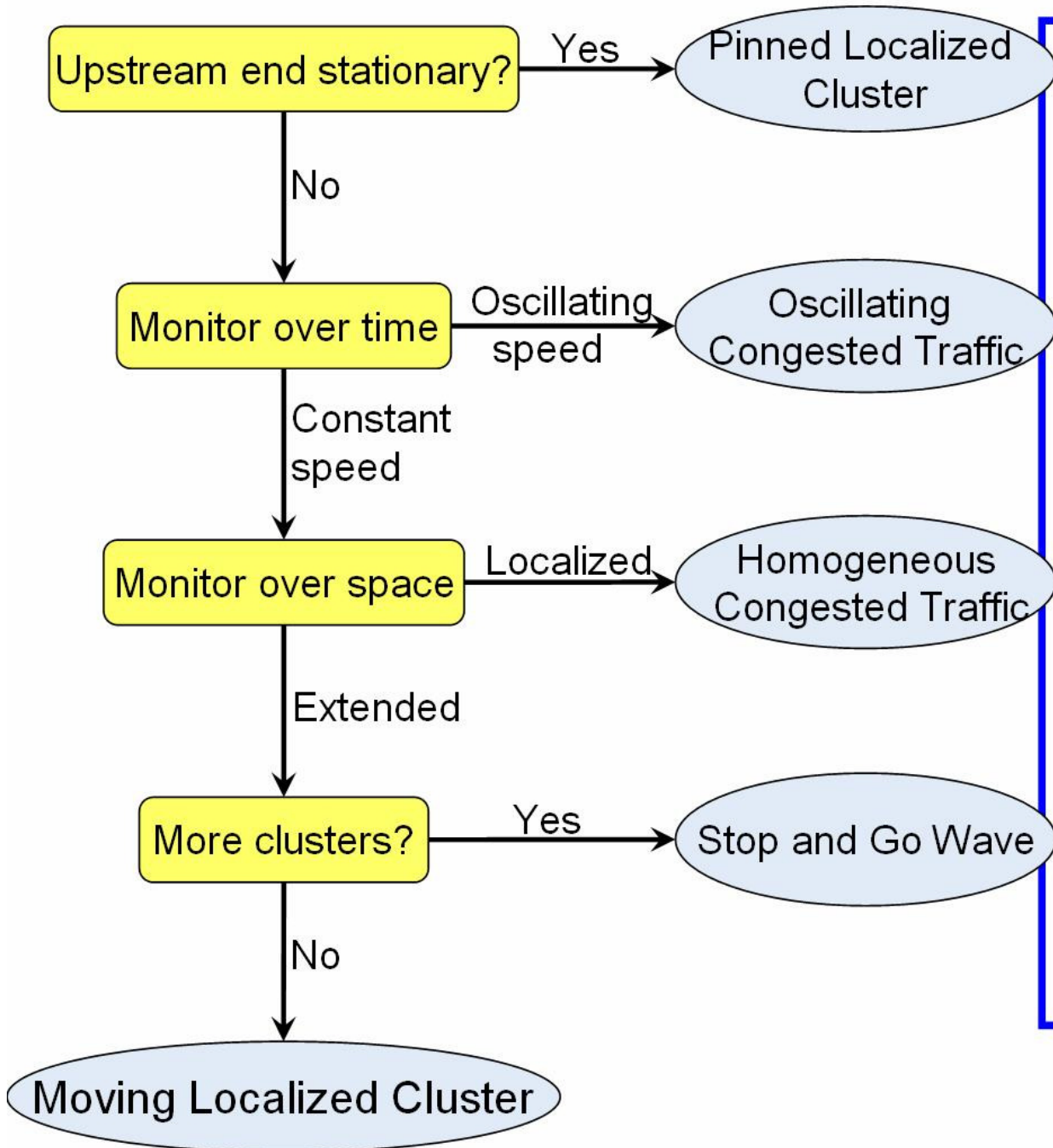


# Recognizing Traffic Structures

- Local Rules to Detect Regional Structures
- Data Aggregation & Classification of High Level Structures



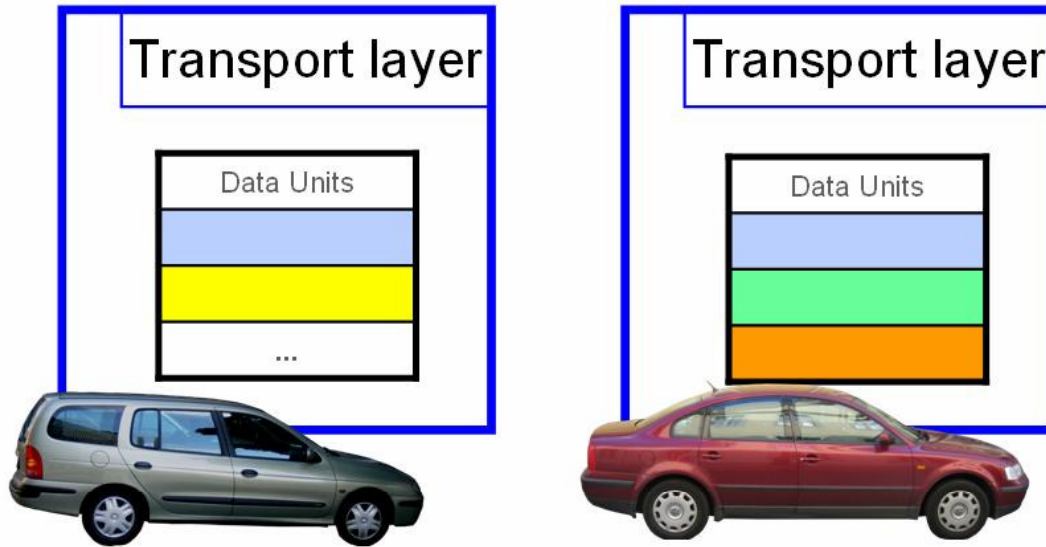
## Decision Tree for Traffic Jam Type



- Different Types of Traffic Jams
- Monitor Jam's Front and Back by HDCs
- Collect Jam's Internals by Moving HDCs
- Example from Last Slide
  - Stop and Go Waves

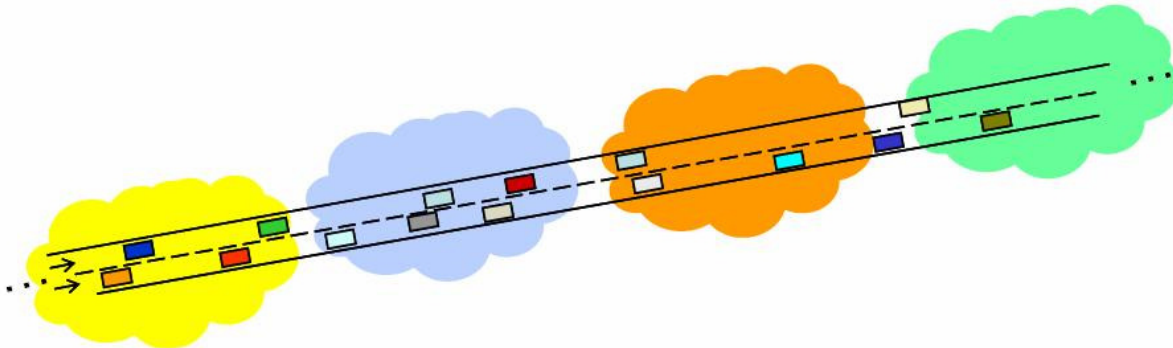
# Transport mechanism for HDCs

AutoNomos



## Design Ideas

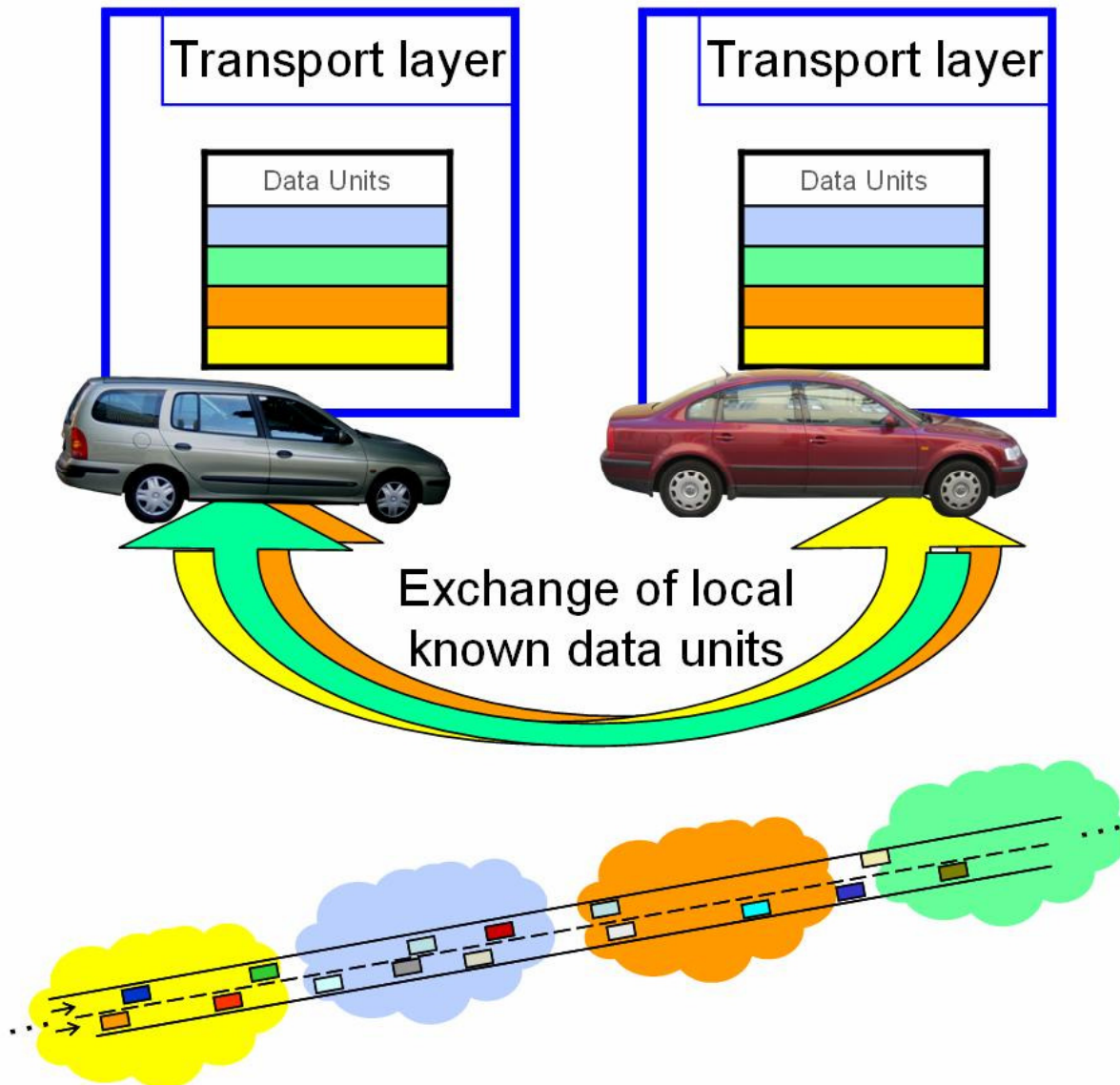
- Data Dissemination Mechanism for new Class of Applications
  - Where Information is more important than Originator
  - Forwarding Nodes do not know each other
- Data Dissemination like Telling Gossip
- Utilize Broadcast Medium, no Unicast Communication
- Simple and Robust
- Priority Control





# Transport mechanism for HDCs

AutoNomos



## Design Ideas

- Data Dissemination Mechanism for new Class of Applications
  - Where Information is more important than Originator
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# Protocols under Evaluation



- Flooding
  - Rebroadcast Data Units immediately but only once
  - Q: What happens, when Network is partitioned
  - Q: What happens when Nodes join later?

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- MILE
  - Broadcast periodically Parts of local known Data Units
  - Q: Is it fast enough?
  - Q: Is the bandwidth consumption too high?

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- MILE on Demand
  - Broadcast periodically full List of Hash Values of Data Units
  - When receive an incomplete List, add Data Unit in next Broadcast
  - Q: What are the Bandwidth savings?
  - Q: Will it be fast enough?

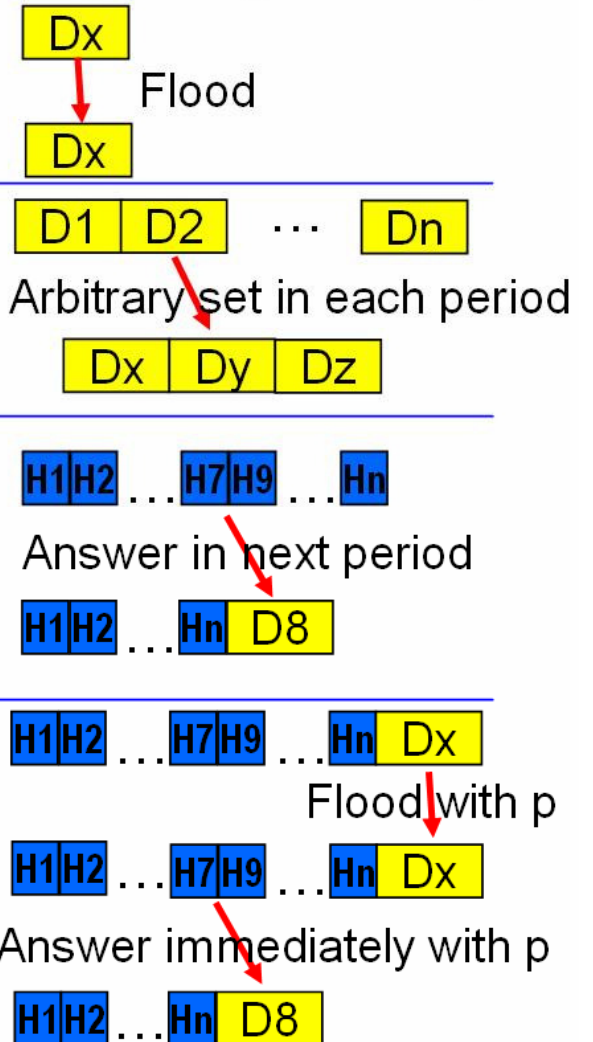
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- AutoCast
  - Probabilistic Flooding depending on Neighborhood Size
  - Broadcast periodically full List of Hash Values of Data Units
  - When receive an incomplete List answer the Data Unit immediately with same probability as Flooding
  - Q: Is it near to the Optimum?
  - Q: Is it scalable?

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- Theoretical optimum
  - Reference only: Nodes intuitively broadcast the required Data Units in the right moment.
  - Reaches as many Nodes as possible

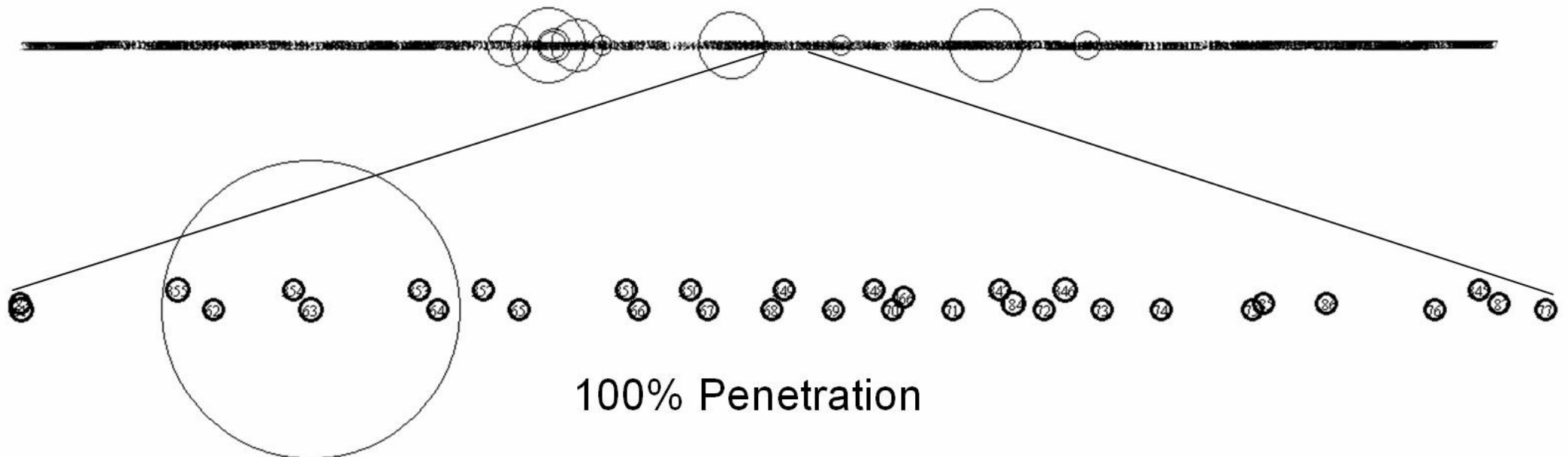
## Message Format



# Simulation Setup

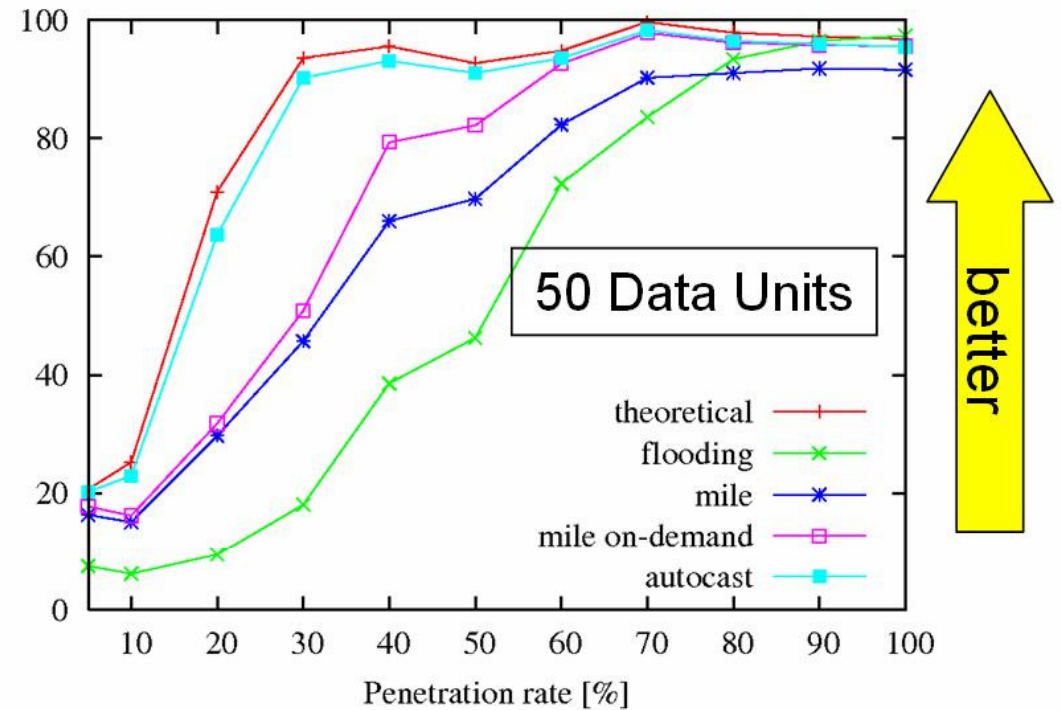
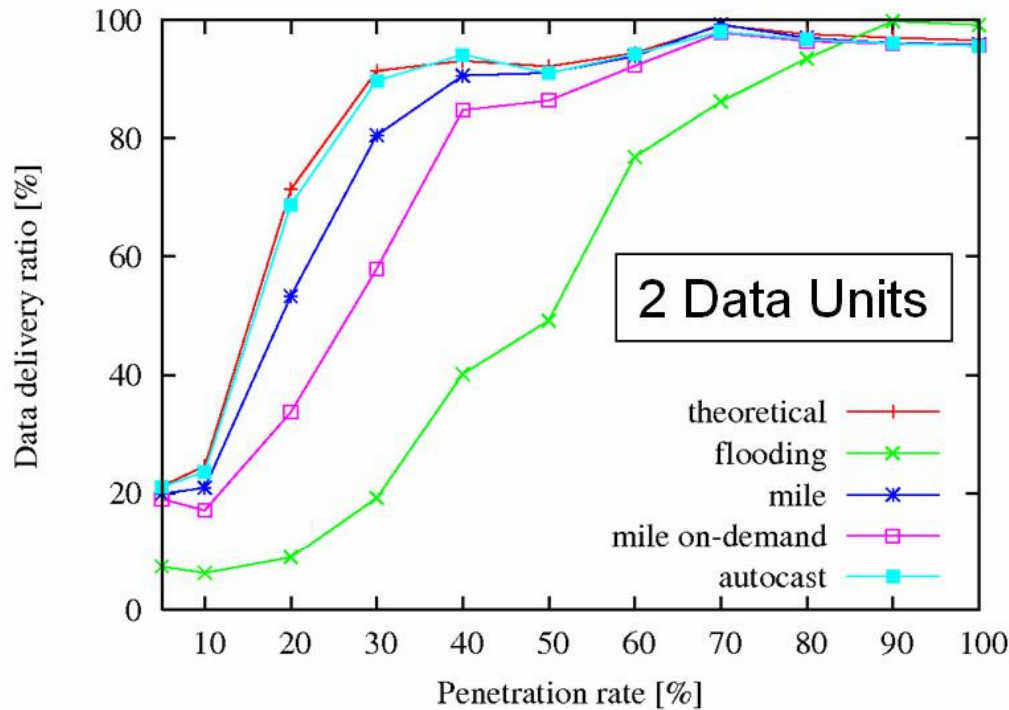
AutoNomos

- Road of 10 km length
- 36 cars/km, 2 lanes in each direction (motorway)
- Penetration rates from 5% to 100%
- Simulator Sumo and ns-2
- Radio: 802.11, 250m radius, 1Mbit/s
- 2 to 50 concurrent Data Units generated at km 5 with lifetime 50s



# Comparison Data delivery

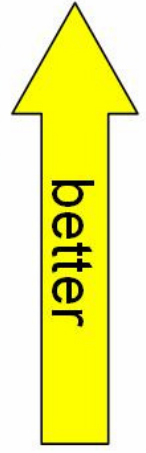
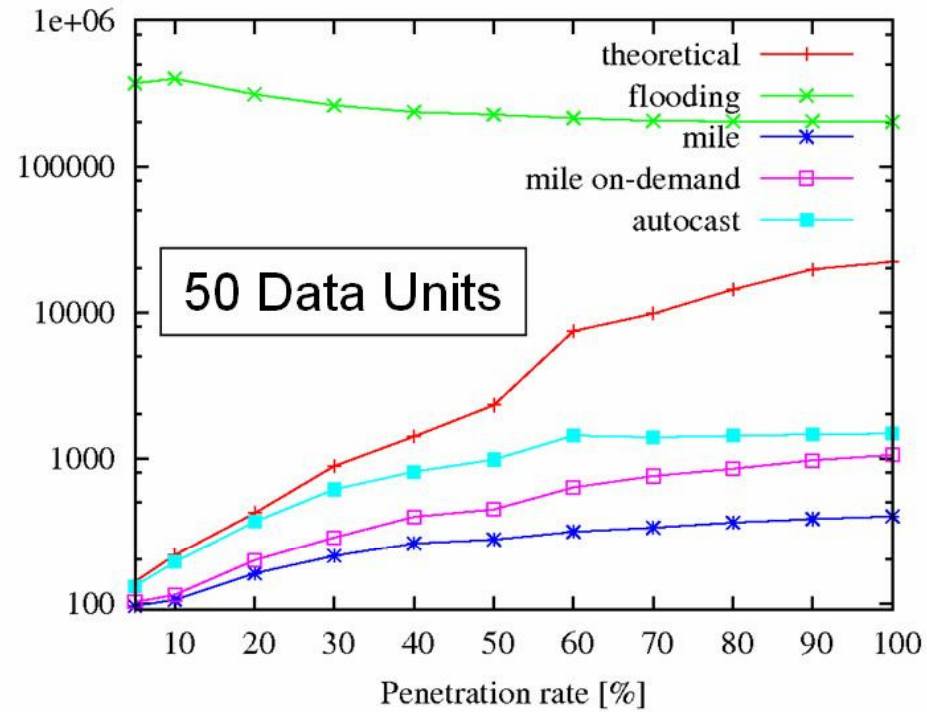
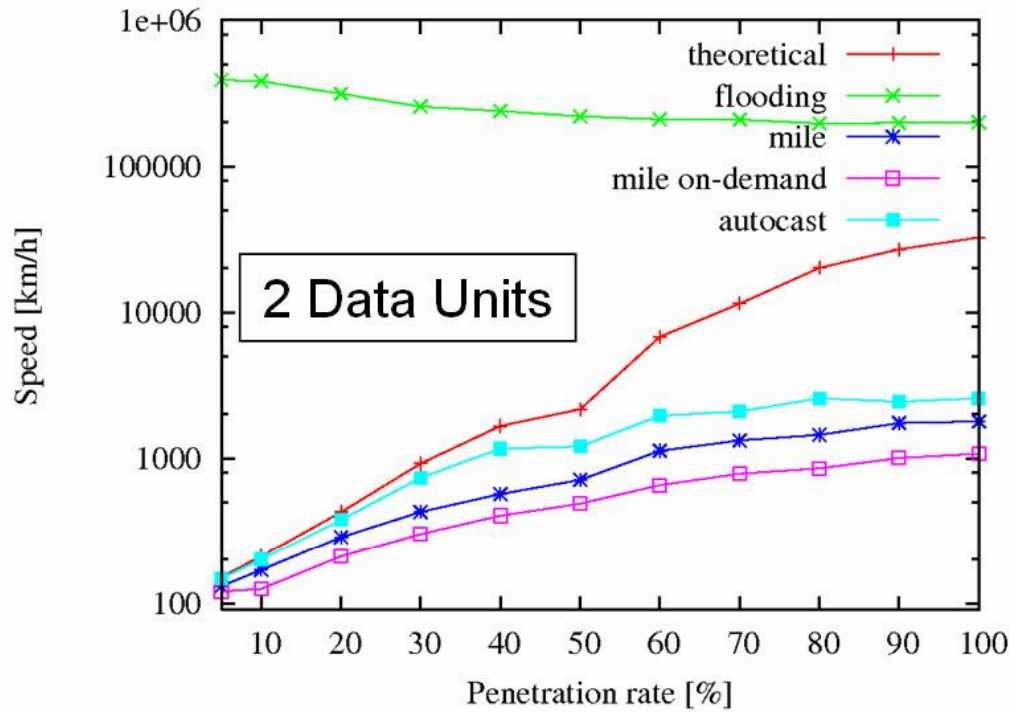
AutoNomos



Protocol	Delivery Ratio	Scalability
Theoretical	Reference	Yes
Flooding	Worst	Yes
MILE	Average	No
MILE on Demand	Bad	Yes
AutoCast	Best	Yes



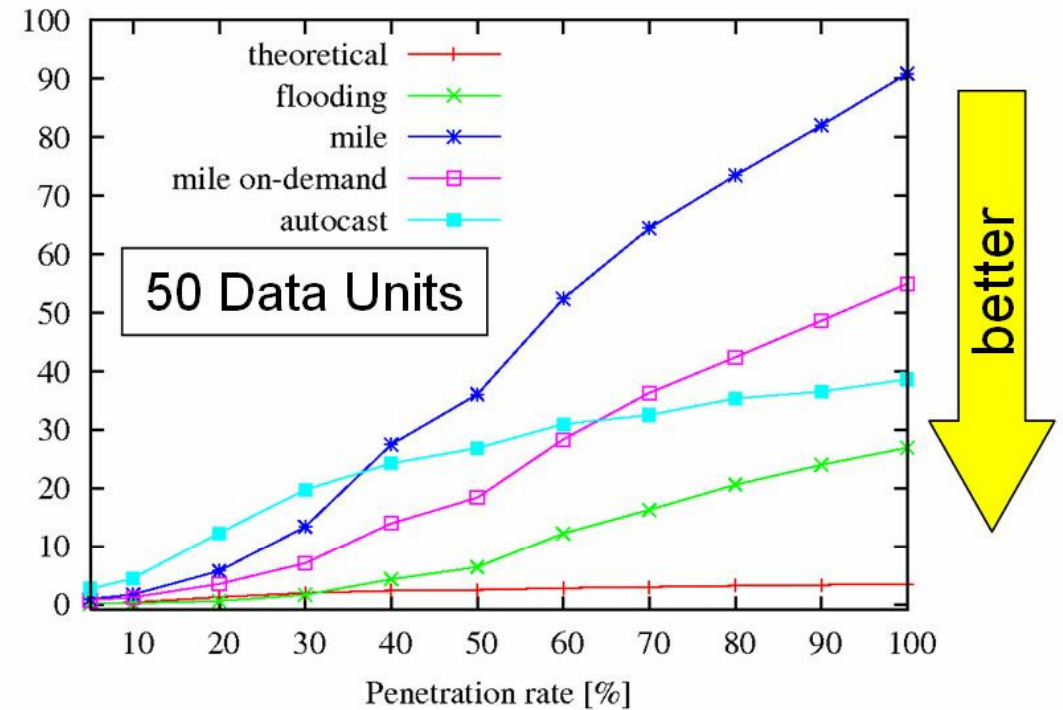
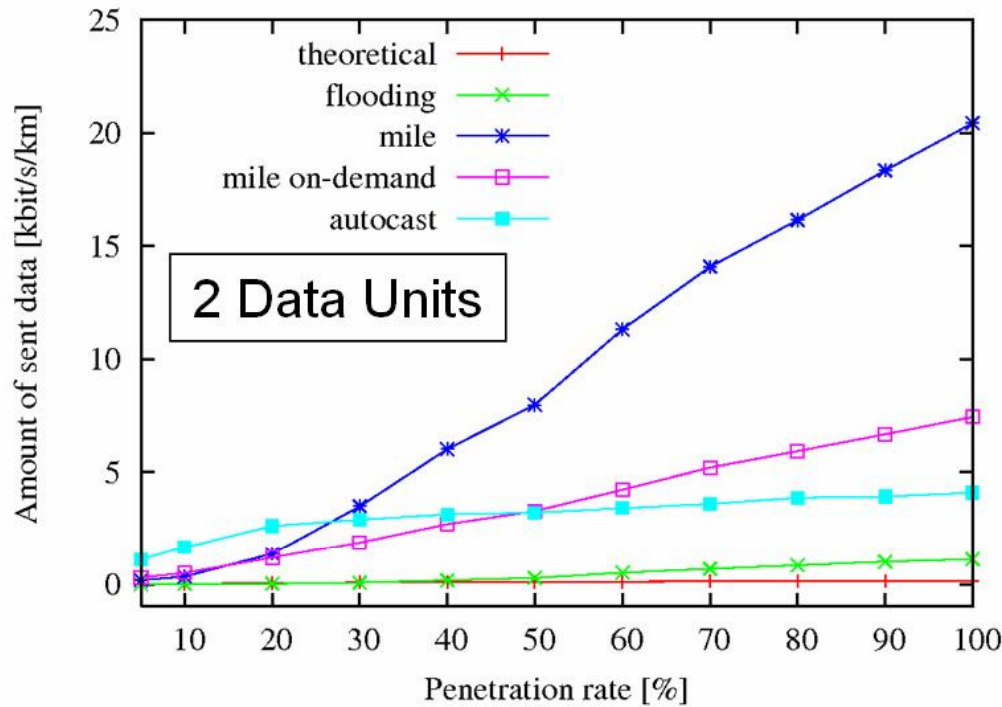
# Comparison Speed



Protocol	Speed	Scalability
Theoretic	Reference	Yes
Flooding	Best	Yes
MILE	Bad	Yes
MILE on Demand	Worst	Yes
AutoCast	Average	Yes

# Comparison Radio Channel usage

AutoNomos



Protocol	Channel Usage	Scalability
Theoretic:	Reference	Yes
Flooding:	Best	No
MILE:	Worst	No
MILE on Demand:	Bad	No
AutoCast:	Average	Yes

# AutoCast – Conclusion

AutoNOMOS

- AutoCast is a good Trade-off between
  - Data Dissemination speed
  - Communication Overhead
  - and Delivery Ratio.
- Good Efficiency in Comparison to Theoretical Optimal Reference
- 802.11 (1 Mbps): less than 5 % of Bandwidth (high density & 50 data units)
- AutoCast adapts to changing Conditions in a Self-Organizing Manner



# Traffic Jam Demonstrator

AutoNomos

- 10 Lego Mindstorms Vehicles
- Based on Student Thesis
  - Communication via Bluetooth
  - Car Following Model

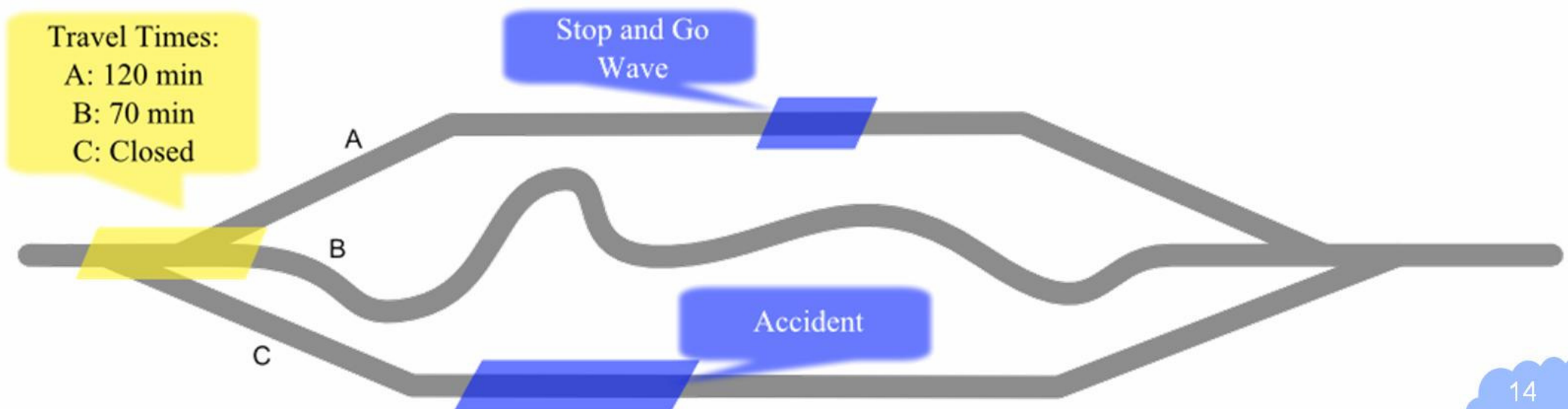
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# Structures in Road Networks

AutoNOMOS

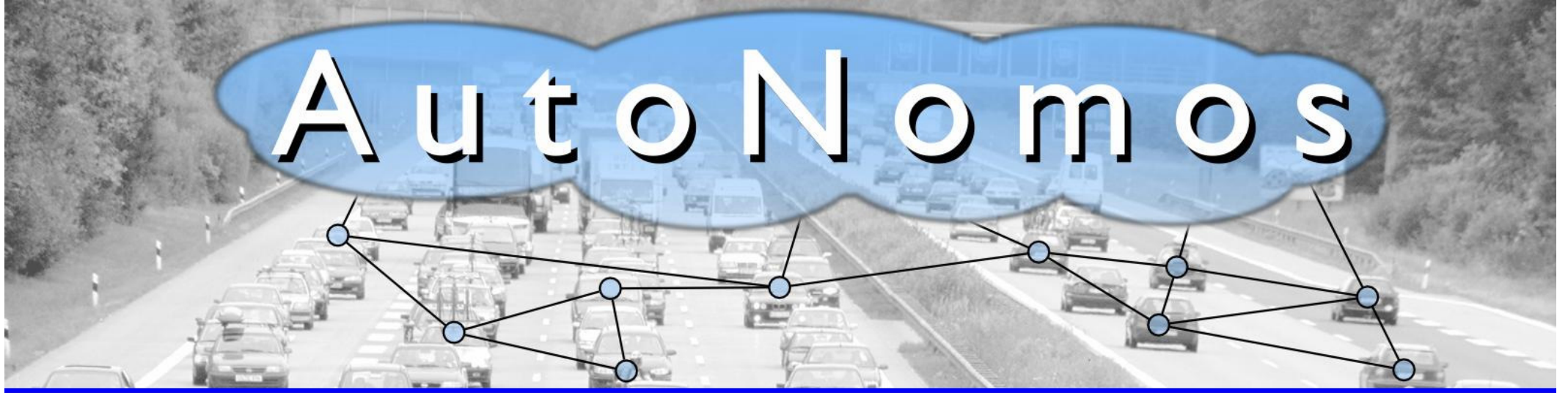
- HDCs in Road Networks
- Network-based Organic Information Complexes
- Hierarchical OICs
- Case Study
  - Road Network (~1000 km, 50.000 vehicles)





- Forecasting of individual Travel Costs
  - Sending “Tracers” along intended Route
- Network-based Computation
  - Forecasting is done everywhere
  - Information is “pushed” to the Driver
- Predicting Changes in global Traffic Flow
  - Anticipate Reaction of Drivers to Traffic Information
- Personalized dynamic Routing

# A u t o N o m o s



**Thank you for your attention**

Questions?



**Stefan Fischer**  
**Axel Wegener**  
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